## A Simple Boosting Framework for Transshipment

Goran Zuzic

ETH Zürich

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## Original motivation

We want to solve the **single-source shortest path** problem (SSSP).

• Given an undirected graph where edges have weights. Compute shortest path from source to all other nodes.



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One of the oldest problems in computer science. Sequential setting .. easy! Dijkstra's famous  $\tilde{O}(m + n)$ -time algorithm is optimal (modulo log).

What about parallel or distributed settings? The problem seems much harder: Dijkstra fails miserably.

In these settings, significant progress has been made on the  $(1 + \varepsilon)$ -approximate shortest path problem.

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• Hopset: Add a small number of edges to a graph such that original shortest paths are  $(1 + \varepsilon)$ -approximated with new paths with small number of hops. (Figure taken from Cohen'00)



In these settings, significant progress has been made on the  $(1 + \varepsilon)$ -approximate shortest path problem.

Main ideas:

• Continuous optimization: (Today) Generalize the shortest path to transshipment. Find an bad approximate solution and boost it to an  $(1 + \varepsilon)$ -approximate.

Recent results based on **continuous optimization**.



## Parallel. $(1 + \varepsilon)$ -apx with $\tilde{O}(1)$ depth and $\tilde{O}(m)$ work.

 $(1 + \varepsilon)$ -apx deterministic with  $\tilde{O}(1)$  depth and  $\tilde{O}(m)$  work.

Distributed.

[Li; 2020] [ASZ; 2020] [RGHZL; 2022] Recent results based on **continuous optimization**.



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[Li; 2020] [ASZ; 2020] [RGHZL; 2022]

#### Distributed.

 $(1 + \varepsilon)$ -apx in  $OPT(G) \cdot n^{o(1)}$  rounds.

[ZGYHS'22].

## Introduction

## 2 Main Aspects of the Solution

- Idea 1: Transshipment generalizes shortest path
- Notation: Consider the LP primal-dual formulation
- Idea 2: Transshipment boosting with duals
- Idea 3: Multiplicative weights
- Idea 4: Self-reduction of transshipment and consequences

## 3 Conclusion

Transshipment.

<u>Transshipment.</u> Given a graph G = (V, E) and a demand vector  $d \in \mathbb{R}^V$  satisfying  $\sum_{v} d(v) = 0$ . Find a flow of minimum cost that satisfies the demands.

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Also known as: uncapacitated min-cost flow, earth mover's distance, Wasserstein metric, optimal transport, transshipment.

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<u>Note.</u> Generalizes (s - t) shortest path. (Also generalizes SSSP.)



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Write the graph G = (V, E) using the <u>node-edge incidence matrix</u> *B*. Steps: (1) Orient edges arbitrarily. (2) For each arc, add column to *B*.



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$$\min_f \|f\|_1 : Bf = d$$

 $f_e = 0$  if no flow along e

 $f_e > 0$  if flow in same direction as e

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$$B = \begin{matrix} \mathbf{v}_1 & \mathbf{e}_2 & \mathbf{e}_3 & \cdots \\ \mathbf{v}_2 & +1 & \cdots \\ \mathbf{v}_4 & +1 & \cdots \\ \mathbf{v}_5 & -1 & \cdots \\ -1 & -1 & \cdots \end{matrix}$$

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$$\mathsf{max}_{\phi} \ \left\langle \boldsymbol{d}, \boldsymbol{\phi} \right\rangle: \left\| \boldsymbol{B}^\top \boldsymbol{\phi} \right\|_\infty \leq 1.$$

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$$\begin{split} \phi_{v} &= \text{potential (height) of } v \\ (B^{T}\phi)_{e} &= \phi_{a} - \phi_{b} \text{ is height difference} \end{split}$$

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Theorem ([Sherman; 2013], [BFKL; 2016], [Zuzic; unpublished])

Fix G. Suppose we are given an oracle  $O_G(\cdot)$  which, given a demand d, outputs an  $\alpha$ -approximate feasible dual  $O_G(d)$ . There is an algorithm that produces a  $(1 + \varepsilon)$ -approximate feasible dual by calling  $O_G(\cdot)$  at most  $poly(\alpha, \varepsilon^{-1}, \log n)$  times.

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#### Corollary

Given such a (dual)  $n^{o(1)}$ -approximation oracle, we can solve  $(1 + \frac{1}{n^{o(1)}})$ -approximate transshipment in  $n^{o(1)}$  oracle calls.

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Question: How many oracle calls?



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**Dual:** 
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 $\begin{array}{ll} \mathsf{Dual:} & \max_{\phi} & \langle d, \phi \rangle \text{ such that } \left\| B^{\top} \phi \right\|_{\infty} \leq 1 \\ \\ \mathsf{Binary search } g: & \exists \phi, \quad \langle d, \phi \rangle \geq g, \quad \left\| B^{\top} \phi \right\|_{\infty} \leq 1 \end{array}$ 

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Dual:	$max_\phi$	$\langle d, \phi  angle$ such that $\left\  B^{ op} \phi \right\ _{\infty} \leq 1$
Binary search g:	$\exists \phi,$	$\langle \boldsymbol{d}, \phi  angle \geq \boldsymbol{g},  \left\  \boldsymbol{B}^{ op} \phi  ight\ _{\infty} \leq 1$
Rewrite:	$\exists \phi,$	$rac{1}{g}\left\langle d,\phi ight angle \geq1\geq\left\Vert B^{ op}\phi ight\Vert _{\infty}$
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Rewrite:	$\exists \phi,$	$\left\langle \underbrace{\frac{1}{g}d - Bp}_{q}, \phi \right\rangle \geq \varepsilon$

 $d_{residual}$ 

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Binary search $g$ :	$\exists \phi,$	$\langle \boldsymbol{d}, \phi  angle \geq \boldsymbol{g},  \left\  \boldsymbol{B}^{ op} \phi  ight\ _{\infty} \leq 1$
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		$d_{ m residual}$
<b>Oregola:</b> $\exists A = \langle A \rangle = A$ Note: erector width $a > \  PT_A \ $		

**Oracle:**  $\exists \phi$ ,  $\langle d_{\text{residual}}, \phi \rangle \geq \varepsilon$ . Note: <u>oracle width</u>  $\rho \geq \|B'\phi\|_{\infty}$ 

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Rewrite:	$\exists \phi,$	$\left\langle \underbrace{\frac{1}{g}d - Bp}_{d_{residual}}, \phi \right\rangle \geq \varepsilon$
<b>Oracle:</b> $\exists \phi$ , $\langle d_{residual}, \phi \rangle \geq \varepsilon$ . Note: <u>oracle width</u> $\rho \geq \left\  B^T \phi \right\ _{\infty}$		
<b>Equiv:</b> $\exists \phi$ , $\langle d_{\text{residual}}, \phi \rangle$	$\rangle \geq \varepsilon / \rho,$	$\ B^{T}\phi\ _{\infty} \leq 1$

$$\textbf{Oracle: } \exists \phi, \quad \left\langle \textit{d}_{\mathsf{residual}}, \phi \right\rangle \geq \varepsilon / \rho, \quad \left\| \textit{B}^{\, \mathsf{T}} \phi \right\|_{\infty} \leq 1$$

Notes:

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$$\exists \phi, \quad \langle d_{\mathsf{residual}}, \phi \rangle \geq \varepsilon / (\boldsymbol{\alpha} \cdot \rho), \quad \left\| B^{\mathsf{T}} \phi \right\|_{\infty} \leq 1$$

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- Q: What if there is no solution to the new problem? Ans: Look at primal and prove the original problem has no solution.
- Computationally, we start with the dual LP and end with a dual LP. Result: <u>Any</u> α-approximate <u>dual</u> solver can be boosted to (1 + ε)-approximate dual solver. Runtime: poly(α, ε<sup>-1</sup>, log n) query calls.



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